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Azimuth Position

Control System

Antenna Potentiometer

Fixed field $e_m(t)$

Armature Gear Layout

Potentiometer $e_i(t)$

Desired azimuth angle

input Differential

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amplifier and power
amplifier Motor

Schematic Desired

azimuth angle input

$e_i(t)$ n-turn

potentiometer 80 (t)

Azimuth angle output

Differential

preamplifier Power

amplifier $v_p(t)$ $e_a(t)$

$V_i(t) + v_o(t) - \text{kg-m}^2 \text{ N-}$

$\text{m s/rad V-s/rad N-m/A}$

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approaches are
available for the
analysis and design of
feedback control
systems The first,
which we began to
study in Chapter 2, is
known as the classical,
or frequency-

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